

training exercises themselves, supporting the rehabilitation process. We collaborate with physical therapists of a children’s hospital to design a system that uses pneumatic artificial muscles (PAMs) to help children with cerebral palsy train their plantar flexor muscles (Figure 1). We present an initial experimental prototype validated with physical therapists and doctors. We also show a feasibility test with patients with informed consent from parents and monitored by the physical therapists.

CCS CONCEPTS

• **Computer systems organization** → **Embedded systems**; *Redundancy*; Robotics; • **Networks** → Network reliability.

KEYWORDS

Home rehabilitation, children with cerebral palsy, soft exoskeleton, artificial muscles

ACM Reference Format:

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1 MOTIVATION

Seventy-three percent of children with cerebral palsy have difficulty walking, and the situation gets worse with age [11, 16, 18, 23]. Early rehabilitation training is the only way to recover and is vital to their future development, preventing walking problems as adults [2, 24]. The most crucial rehabilitation session for children with cerebral palsy is physical therapy. The one-to-one physical therapist training, including muscle stretching and other sessions, is very effective yet also time-consuming [10, 13, 15]. Rehabilitation practitioners generally formulate 4–6 family rehabilitation training movements for each child with cerebral palsy [3, 20]. These contents are usually expressed in medical professional terms. Then, the rehabilitation therapists demonstrate each action for the parents of the cerebral palsy child, and the parents usually record these rehabilitation actions by taking photos or videos. So in the next three months, parents would act as rehabilitation therapists and do rehabilitation training for their children with cerebral palsy. When their children with cerebral palsy can achieve the goals set by the therapist before, they return to the hospital for review. Then, the physical therapist will develop a new rehabilitation plan. There are also some effective parents community and support efforts [5, 27, 34]. However, the muscle stretching exercises and rehab plans are quite traditional and the basic processes have not been changed in many years.

There are a couple of efforts using novel therapy approaches, exoskeletons, and other mechanical designs to help the rehabilitation process, yet most of them are rather large, expensive and require a large amount of power/air pressure etc. [7, 27, 28, 30, 31]. There are also a lot of works using lower-limb exoskeletons and artificial muscles for rehabilitation purposes [1, 4, 9, 12, 17, 19, 22, 25, 26, 32].

In our research, we work towards novel rehabilitation solutions for cerebral palsy and want to support the process on several scales in the hospital and at home. Especially, we investigate wearable

actuators and soft materials (like the pneumatic gel muscles) as a new, unobtrusive, affordable opportunity for children with cerebral palsy to help them perform rehabilitation training exercises [8, 29]. We hope that our research will allow more children with cerebral palsy to get opportunities for rehabilitation exercises, liberate parents’ hands in family rehabilitation scenarios, improve family rehabilitation efficiency, shorten rehabilitation time, and reduce rehabilitation costs. This work is an initial step towards a novel rehabilitation solution, a soft exoskeleton system for children with cerebral palsy applicable in a home setting.

The contributions of this work on cerebral palsy rehabilitation are: (1) we present a novel soft exoskeleton rehabilitation prototype based on a low-pressure type PAM called Pneumatic Gel Muscle (PGM) for children with cerebral palsy, (2) we present an experimental protocol applying the prototype to plantar flexor muscle stretching comparing it to a physical therapist stretch. (3) We present an initial feasibility test with 3 patients (under supervision of 2 doctors and a physical therapist), as well as discussing future improvements and potential issues.

2 APPROACH AND ETHICAL CONSIDERATIONS

Since we are interested in the complexity of cerebral palsy rehabilitation exercises, we conducted ethnography research, including observations of cognitive assessment, cerebral palsy screening, rehabilitation course observation, expert interviews, cerebral palsy rehabilitation-related documents, and review of rehabilitation aids. Before starting the research to inform the design, we went to our partner children’s hospitals and observed daily rehabilitation training for three months to insight research opportunities. We observed different rehabilitation courses to understand clinical rehabilitation, focusing on the interaction between cerebral palsy children and rehabilitation experts during rehabilitation training, including the use of equipment, the time of each rehabilitation action, and how to attract the child to complete a certain action.

Our hospital rehabilitation observation found that plantar flexor muscle stretching is essential for most children with cerebral palsy [11, 14]. So we decided first to focus on applying pneumatic gel muscles (PGMs) to rehabilitate the ankle movement. Another difficulty is that when parents recover their children at home, they cannot achieve accurate rehabilitation actions like a therapist. Therefore, the accuracy of rehabilitation training is what we are exploring and solving with PGM equipment. As a background, we described the rehabilitation process from the perspective of multiple rehabilitation experts who make rehabilitation plans for children with cerebral palsy. We have observed the rehabilitation treatment of children with cerebral palsy and analyzed which muscle training is essential to better provide information for designing our artificial muscles’ system. A major concern for conducting experiments is not to interfere with the rehabilitation process of the children and to ensure the safety of the children when using our research prototypes. To this end we discussed potential experimental setups with doctors and ethical board members at all institutions involved. Our Ethics proposal containing the experimental design and the PGM system description have been approved by the ethics committees

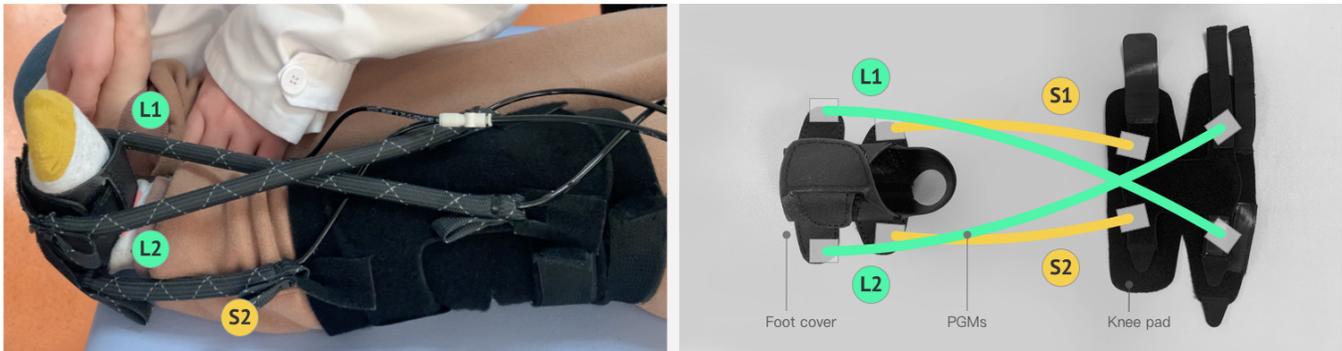


Figure 2: PGM foot cover and Knee pad. "L1" and "L2" are the longer PGMs, "S1" and "S2" are the shorter ones.

from both the partner hospital and university as well as external engineering and medical advisors.

3 PNEUMATIC ARTIFICIAL MUSCLE PROTOTYPE DESIGN

Together with physical therapists, we designed and refined our functional PGM prototype. Before applying it to children, we did several pre-tests on multiple adults, including a physical therapist, as well as demonstrations to the parents. Our system uses four pneumatic gel muscles (PGM) as soft actuators worn by the user on their leg. Total weight of the system excluding the air pressure source is around 400g (including four PGMs of weight 86g).

The PGMs we use can be activated with low air pressure and have been used in related work for soft exoskeletons in training and other rehabilitation research by Ogawa et al., Takashi et al. and others [6, 21, 29, 33]. Each PGM is either actuated or deflated through a dedicated 3/2 solenoid valve, operated in normally-closed configuration. The solenoid valve used in our device is the SYJ312M-SLZD-M3 (SMC) with an operating pressure range of 0-0.7MPa. Our device does not require to use a stationary air compressor, instead we can opt for a NTG mini CO₂ gas cylinder (with a gas volume of 74 grams). The cylinder is attached to a regulator used to maintain an input air pressure of 0.2MPa to the solenoid valves. One charge can work for up to 500 muscle contractions. Our device is controlled via a ESP32 microcontroller. The air pressure to the PGMs can be controlled individually, although in the current setup we activate them together (only stretch an relax state). Therefore, the microcontroller can receive instructions over wifi/bluetooth or USB connection and actuates the corresponding channels to energize or de-energize the solenoid valves. The system also offers a stand-alone mode, in which the stretching programs can be loaded directly into the micro-controller (used in the experimental setup). The program can be started and stopped over a simple button-press.

We tested the prototype under the supervision of the physical therapist together with 3 children (aged 3, 6 and 9). The prototype is functional and can be adjusted to stretch the plantar flexor muscle in a similar fashion as the physical therapist does.

Four PGMs with two different lengths were used in our experiment. We also designed a special foot cover and a knee pad for fixing the PGMs by Velcro. The function of the two longer PGMs which are crossed with each other is responsible for the stretching,

and the two shorter ones are used for safety consideration (2). One side of the longer PGMs is fixed on the knee pad's upper part, and another side is fixed on the upper part of the foot cover. One side of the shorter ones is fixed on the lower part of the knee pad, and another side is fixed on the lower part of the foot cover. We used the CO₂ gas cylinders to actuate the PGMs and maintained the air pressure at max 0.2MPa to ensure the safety of the experiment using over-pressure valves.

4 CONCLUSION AND FUTURE WORK

We designed a lower-limb rehabilitation system for children with cerebral palsy to train their plantar flexor muscles by applying pneumatic artificial muscles. After the initial tests, we will now move forward to conduct a control experiment on children with cerebral palsy, using PGM to imitate the same movement performed by physical therapists and comparing the rehabilitation effect between the physical therapists and PGM. We hope to show that PGM stretching can be an effective alternative for cerebral palsy rehabilitation.

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